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the result. The book begins with a discussion of the physics of dynamic systems comprised of particles, rigid bodies, and deformable bodies and the physics and mathematics for the analysis of a system with a single-degree-of-freedom. It develops mathematical models using energy methods and presents the

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mathematical foundation for the framework. The author illustrates the development and analysis of linear operators used in various problems and the formulation of the differential equations governing the response of a conservative linear system in terms of self-adjoint linear operators, the inertia operator, and the

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stiffness operator. The author focuses on the free response of linear conservative systems and the free response of non-self-adjoint systems. He explores three methods for determining the forced response and approximate methods of solution for continuous systems. The use of the mathematical foundation and the

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The aim of this book is to impart a sound understanding, both physical and mathematical, of the fundamental theory of vibration and its applications. The book

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presents in a simple and systematic manner techniques that can easily be applied to the analysis of vibration of mechanical and structural systems. Unlike other texts on vibrations, the approach is general, based on the conservation of energy and Lagrangian dynamics, and develops specific techniques from these

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As engineering systems become more

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increasingly interdisciplinary, knowledge of both mechanical and electrical systems has become an asset within the field of engineering. All engineers should have general facility with modeling of dynamic systems and determining their response and it is the objective of this book to provide a framework for that

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Understanding. The study material is presented in four distinct parts; the mathematical modeling of dynamic systems, the mathematical solution of the differential equations and integro differential equations obtained during the modeling process, the response of dynamic systems, and an introduction to

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feedback control systems and their analysis. An Appendix is provided with a short introduction to MATLAB as it is frequently used within the text as a computational tool, a programming tool, and a graphical tool. SIMULINK, a MATLAB based simulation and modeling tool, is discussed in chapters where the

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development of models use either the transfer function approach or the state-space method.

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